



# Polylogarithmic Time Algorithms for Shortest Path Forests in Programmable Matter

**Andreas Padalkin**, Christian Scheideler

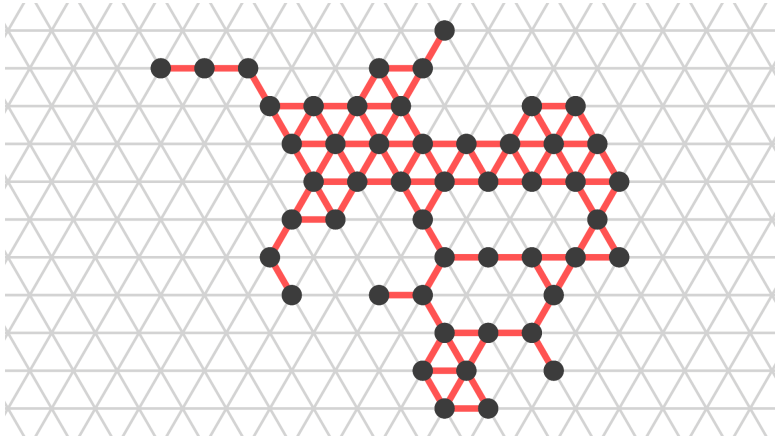
Initialized at the Dagstuhl Seminar 23091 “Algorithmic Foundations of Programmable Matter”

Thanks to

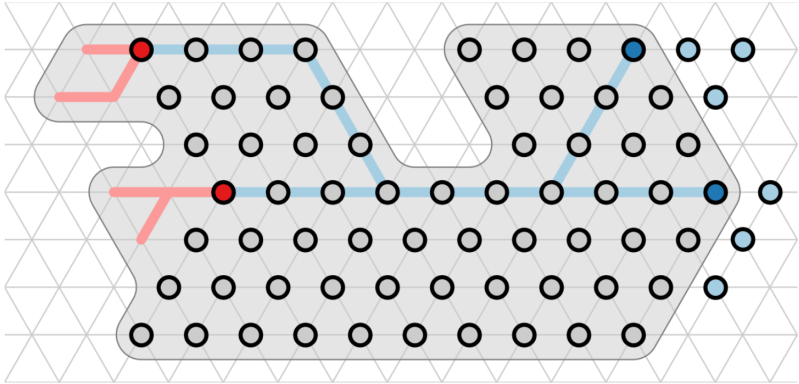
Shantanu Das, Yuval Emek, Maria Kokkou, Irina Kostitsyna, Tom Peters, Andrea Richa

Supported by the DFG Project SCHE 1592/10-1

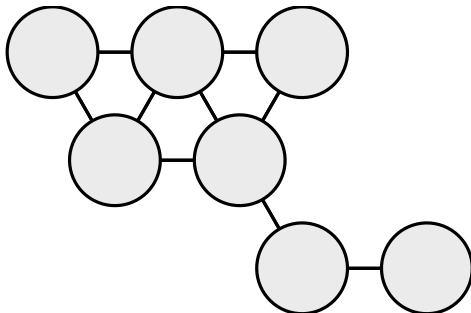
# Geometric Amoebot Model



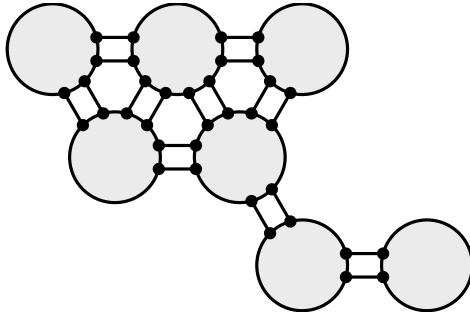
## Shortest Paths in the Amoebot Model



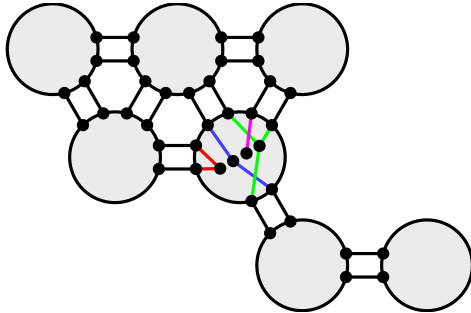
Kostitsyna, Peters, Speckmann:  
Fast Reconfiguration for Programmable Matter.  
DISC 2023



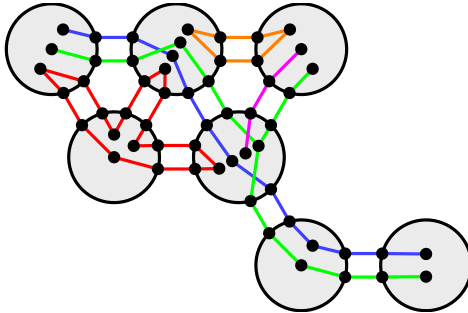
## Reconfigurable Circuit Extension



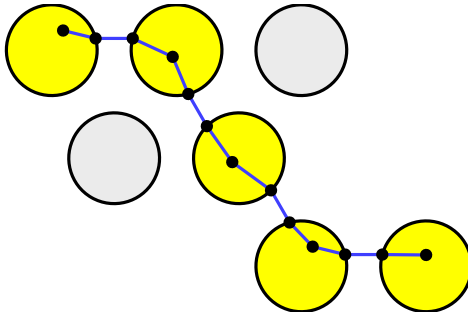
# Reconfigurable Circuit Extension



# Reconfigurable Circuit Extension



## Reconfigurable Circuit Extension

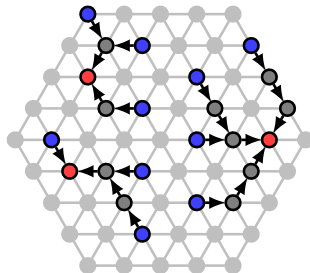




## Shortest Path Forest Problem

$(k, \ell)$ -shortest path forest problem

- Given:  $k$  sources,  $\ell$  destinations
- Goal: compute a shortest path from each destination to the closest source



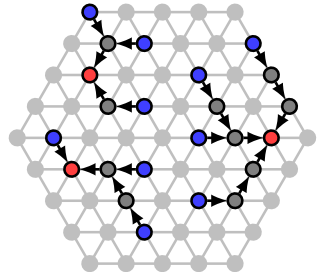
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Assumptions

- No holes
- Leader
- Common chirality/compass orientation



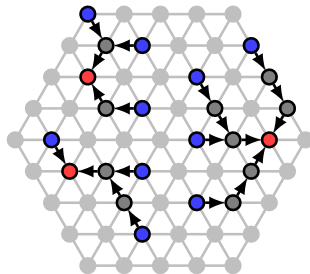
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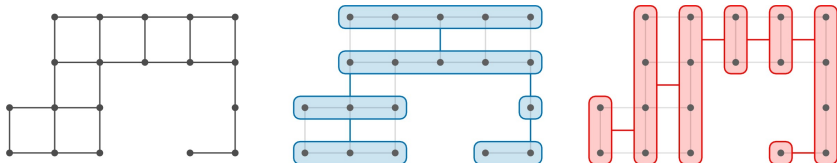
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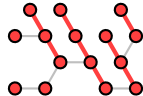
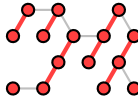
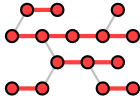
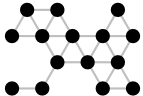
Sources	Destinations	Runtime
1	$\ell$	$O(\log \ell)$
$k$	$\ell$	$O(\log n \log^2 k)$

$$\text{dist}(u, v) = \text{dist}_x(u, v) + \text{dist}_y(u, v)$$

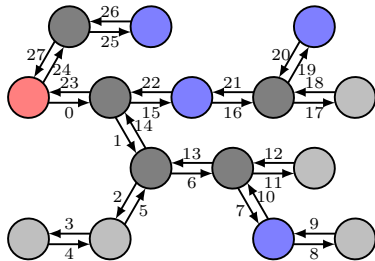
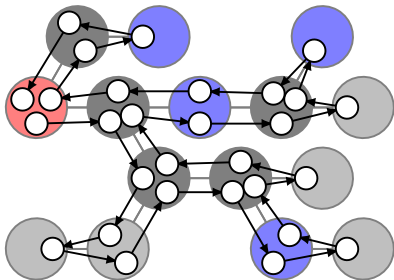


Coy, Czumaj, Scheideler, Schneider, Werthmann:  
Routing schemes for hybrid communication networks.  
Theor. Comput. Sci. 2024

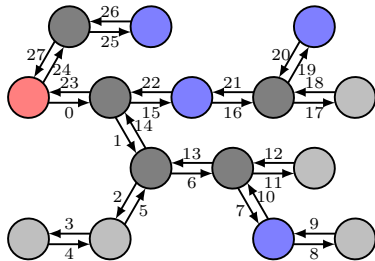
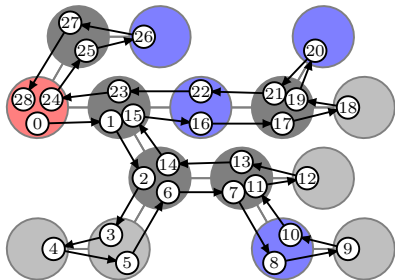
$$2 \cdot \text{dist}(u, v) = \text{dist}_x(u, v) + \text{dist}_y(u, v) + \text{dist}_z(u, v)$$



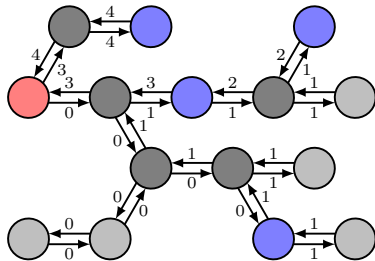
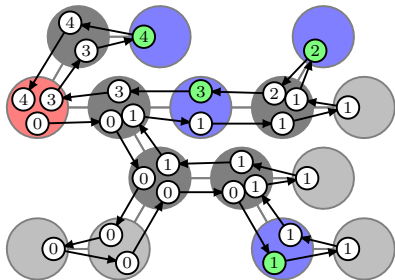
## Euler Tour Technique and PASC Algorithm



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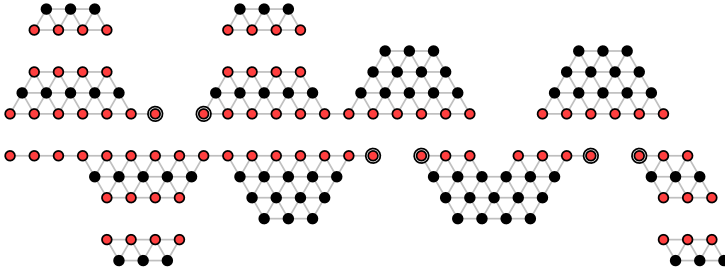
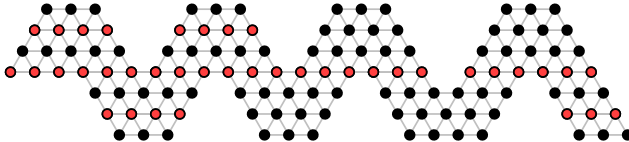
## Euler Tour Technique and PASC Algorithm







# Shortest Path Forest with a Multiple Sources





# Thank you for your attention

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