



Katharina Klost and Wolfgang Mulzer EuroCG 2024

Robust Algorithms for Finding Triangles and Computing the Girth in Unit Disk and Transmission Graphs



Unit Disk Graphs Set of sites $S \subseteq \mathbb{R}^2$



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- $D(S) = (S, E) \text{ with } E = \{\{u, v\} \mid ||uv|| \le 2\}$



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General Disk Graphs Set of sites $S \subseteq \mathbb{R}^2$ with radii r_s D(S) = (S, E) with $E = \{\{u, v\} \mid ||uv|| \le r_s + r_t\}$

Unit Disk Graphs and Transmission Graphs Transmission Graphs Unit Disk Graphs Set of sites $S \subseteq \mathbb{R}^2$ Set of sites $S \subseteq \mathbb{R}^2$ with radii r_s D(S) = (S, E) with $E = \{\{u, v\} \mid ||uv|| \le 2\}$ General Disk Graphs Set of sites $S \subseteq \mathbb{R}^2$ with radii r_s D(S) = (S, E) with $E = \{\{u, v\} \mid ||uv|| \le r_s + r_t\}$



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Usually: Input are the points/disks

Today: Input is an abstract graph (adjacency list)

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 - 1. Input is in domain \rightarrow correct answer
 - 2. Input is **not** in domain \rightarrow no guarantees on output of the algorithm

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Usually: Input are the points/disks Today: Input is an abstract graph (adjacency list) Promise Setting 1. Input is in domain \rightarrow correct answer 2. Input is **not** in domain \rightarrow no guarantees on output of the algorithm Today: Robust Setting [Raghavan, Spinrad; 2003] 1. Input is in domain \rightarrow correct answer 2. Input is **not** in domain \rightarrow *either* correct answer *or* , not in domain " Challenges Transfer from geometric setting to robust setting takes $\Omega(n+m)$ time. Recognizing a unit disk or transmission graph is $\exists \mathbb{R}$ -hard











(General) Disk Graphs: $O(n \log n)$

[Kaplan et al., 2019]

Transmission Graphs: $O(n \log n)$ expected

?

[Kaplan et al., 2019]







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NEW

Robust Setting

Unit Disk Graphs: O(n)

Transmission Graphs: O(n+m)NEW





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Geometric Setting

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Transmission Graphs: O(n+m)NEW



Geometric Setting

(General) Disk Graphs: $O(n \log n)$ expected

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Robust Setting Unit Disk Graphs: O(n)





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Lemma Vertex v with $deg(v) \ge 6$ in unit disk graph has triangle with two of any six neighbors.

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report triangle



not a unit disk graph

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Theorem There is a robust algorithm that finds a triangle in a unit disk graph in O(n) time.

Case 2: At least one vertex v with $deg(v) \ge 6$



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 $N_{\rm in}(v)$ ingoing neighbors



 $N_{\rm in}(v)$ ingoing neighbors

 $N_{out}(v)$ outgoing neighbors



- -

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 $N_{out}(v)$ outgoing neighbors

 $N_{\rm bi}(v) = N_{\rm in} \cap N_{\rm out}$



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Lemma In a transmission graph, if there is a vertex with $|N_{\rm bi}(v)| \ge 6$ then two among every six of those vertices form a triangle.



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Lemma: Every directed cycle in a transmission graph has at least one - edge.

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Compute $N_{\rm bi}(v)$ for all $v \in V$ O(n+m)

Case 1: $|N_{\rm bi}(v)| < 6$ for all vertices



if not acyclic \rightarrow no transmission graph O(n+m)



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a)

report triangle



no transmission graph





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Triangle Detection in Transmission Graphs Algorithm Compute $N_{\rm bi}(v)$ for all $v \in V$ O(n+m)

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if not acyclic \rightarrow *no transmission graph* O(n+m)



explicitly check for \boldsymbol{v} with $N_{\mathsf{bi}}(v) \neq \emptyset$ O(n+m)

Theorem There is a robust algorithm that finds a triangle in a transmission graph in O(n+m) time.





Conclusion Robust Algorithms for: Triangles in unit disk graphs O(n)Triangles in transmission graphs O(n+m)Girth in unit disk graphs O(n)





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Lemma_[Evans et al., 2016] If a (unit) disk graph has no triangle, it is planar.

Algorithm





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yes

girth algorithm for planar graphs

[Chang, Lu; 2013]









Theorem There is a robust algorithm that computes the girth of a unit disk

