# A variant of backwards analysis applicable to order-dependent sets



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- n elements
- randomization order  $\sigma \in S_n$
- $T_i$ : running time of the *i*-th step
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- Many other applications [Boissonnat and Yvinec, 1998]:
- Popularized by [Seidel, 1993] provides a "bad example", where backwards analysis is not applicable
- Key requirement: algorithm's output is independent of the randomization order

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$$G_{\sigma} = \begin{cases} \frac{\sigma = (\sigma_{1}, \sigma_{2}, \sigma_{3}, \dots, \sigma_{n-1}, \sigma_{n}) = \sigma^{(n)}}{\sigma^{(1)} = (\sigma_{2}, \sigma_{3}, \dots, \sigma_{n-1}, \sigma_{n}, \sigma_{1})} \\ \sigma^{(2)} = (\sigma_{1}, \sigma_{3}, \dots, \sigma_{n-1}, \sigma_{n}, \sigma_{2}) \\ \dots \\ \sigma^{(i)} = (\sigma_{1}, \dots, \sigma_{i-1}, \sigma_{i+1}, \dots, \sigma_{n}, \sigma_{i}) \\ \dots \\ \sigma^{(n-1)} = (\sigma_{1}, \sigma_{2}, \dots, \sigma_{n-2}, \sigma_{n}, \sigma_{n-1}) \end{cases} \end{cases}$$

A set  $R_n \subset S_n$ , which satisfies  $\bigcup_{\sigma \in R_n} G_\sigma = S_n$  is called **set of representatives**.

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For n = 4, we can choose

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$$E(T_i) = \frac{\sum_{\sigma \in S_i} T_i(\sigma)}{i!} = \frac{\sum_{\sigma \in R_i} \overbrace{T_i(G_{\sigma})}^{\leqslant f(O_i(\sigma))}}{i!}$$

# Why choose this grouping?

• each element appears exactly once as last element

$$G_{\sigma} = \begin{cases} \frac{\sigma = (\sigma_1, \sigma_2, \sigma_3, \dots, \sigma_{n-1}, \sigma_n) = \sigma^{(n)}}{\sigma^{(1)} = (\sigma_2, \sigma_3, \dots, \sigma_{n-1}, \sigma_n, \sigma_1)} \\ \sigma^{(2)} = (\sigma_1, \sigma_3, \dots, \sigma_{n-1}, \sigma_n, \sigma_2) \\ \dots \\ \sigma^{(i)} = (\sigma_1, \dots, \sigma_{i-1}, \sigma_{i+1}, \dots, \sigma_n, \sigma_i) \\ \dots \\ \sigma^{(n-1)} = (\sigma_1, \sigma_2, \dots, \sigma_{n-2}, \sigma_n, \sigma_{n-1}) \end{cases}$$

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- each element appears exactly once as last element
- minimizes the number of inversions between the base permutation σ and the permutations within its group G<sub>σ</sub>
   ⇒ similarity between O<sub>i</sub>(σ) and O<sub>i</sub>(σ<sup>(j)</sup>) for all j ≤ i

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For any fixed dimension, the triangulation algorithm has  $O(n \log n)$  expected time complexity.

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 $\Rightarrow$  Count how many points fall into the deleted triangle in expectation!

# Connection: shifted permutations $\leftrightarrow$ group representative

For  $0 \leq j \leq i \leq n$ , permutation  $\sigma \in S_n$  denote by

- $\mathbf{T}^i_{\sigma}$  partial triangulation after processing *i* many points specified by  $\sigma$
- ${}^{j}A^{i}_{\sigma}$  union of triangles of  $T^{i}_{\sigma}$ , which are incident to point  $p_{\sigma(j)}$
- $\Delta_{\sigma}^{i}$  triangle of  $T_{\sigma}^{i}$ , which contains point  $p_{\sigma(n)}$

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#### Lemma

For all  $1 \leq j \leq i \leq n$  and any permutation  $\sigma \in S_n$  it holds:  $\Delta_{\sigma^{(j)}}^{i-1} \subset {}^j A_{\sigma}^i$ .

For insertion order  $\sigma = (2, 1, 4, 3)$ :



 $T^3_{-(2)}$  with highlighted  $\Delta^3_{\sigma^{(2)}}$ 



 $T_{\sigma}^4$  with highlighted  $^2A_{\sigma}^4$ 

### Corollary

In the *i*-th insertion step, each of the n - i remaining points has to be rebucketed for at most 3 permutations within a group  $G_{\sigma}$  for any  $\sigma \in S_i$ .

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Triangulation expected time complexity:

$$E(T(n)) = \sum_{i=1}^{n} \frac{\sum_{\sigma \in R_i} T_i(G_{\sigma})}{i!} = \sum_{i=1}^{n} O\left(\frac{\sum_{\sigma \in R_i} 3(n-i)}{i!}\right)$$
$$= O\left(\sum_{i=1}^{n} \frac{n}{i}\right) = O(n \log n)$$

#### Voronoi-like diagrams [Junginger and Papadopoulou, 2023]

• intermediate structure in the incremental construction of Voronoi diagrams

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- intermediate structure in the incremental construction of Voronoi diagrams
- perform site-deletion in an abstract Voronoi diagram in linear time
- intermediate Voronoi-like diagrams are order dependent
- final Voronoi-like diagram is oder independent! (it corresponds to a real Voronoi diagram)



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### Looking for other applications!

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# Literature —— Thank you for your attention!

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