## Approximating the Fréchet Distance for Low Highway Dimension Graphs

Anne Driemel and Marena Richter

University of Bonn

EuroCG '24, March 2024

## The Problem

Overall problem
Given: Graph $G$, shortest path $P$, walk $Q$.
Goal: Compute discrete Fréchet distance of $P$ and $Q$.

## The Problem

Overall problem
Given: Graph $G$, shortest path $P$, walk $Q$.
Goal: Compute discrete Fréchet distance of $P$ and $Q$.

## Decision problem

Given: Graph $G$, shortest path $P$, walk $Q, \delta>0$.
Goal: Decide if $D_{\mathcal{F}}(P, Q) \leq \delta$ or $D_{\mathcal{F}}(P, Q)>\delta$.

## The Problem

Overall problem
Given: Graph $G$, shortest path $P$, walk $Q$.
Goal: Compute discrete Fréchet distance of $P$ and $Q$.

## Decision problem

Given: Graph $G$, shortest path $P$, walk $Q, \delta>0$.
Goal: Decide if $D_{\mathcal{F}}(P, Q) \leq \alpha \cdot \delta$ or $D_{\mathcal{F}}(P, Q)>\delta$ for some $\alpha>1$.

## The Problem

Overall problem
Given: Graph $G$, shortest path $P$, walk $Q$.
Goal: Compute discrete Fréchet distance of $P$ and $Q$.

## Decision problem

Given: Graph $G$, shortest path $P$, walk $Q, \delta>0$.
Goal: Decide if $D_{\mathcal{F}}(P, Q) \leq \alpha \cdot \delta$ or $D_{\mathcal{F}}(P, Q)>\delta$ for some $\alpha>1$.
Related work for decision problem:

|  | apx-factor | time |
| :---: | :---: | :---: |
| Driemel, van der Hoog, Rotenberg [2022] | $1+\varepsilon$ | $\mathcal{O}\left(\|G\| \log \|G\| / \sqrt{\varepsilon}+\|P\|+\frac{1}{\varepsilon}\|Q\|\right)$ |
| van der Hoog, Rotenberg, Wong [2023] | $1+\varepsilon$ | $\mathcal{O}\left(\frac{1}{\varepsilon}\|Q\|\left(T_{\text {dist }}+\log \|P\|\right)\right)$ |
| Driemel, Richter [2024] | $\frac{5}{3}+\varepsilon$ | $\mathcal{O}\left(\|P\|+\|Q\|(h \log h)^{2} \log D\right)$ |

$D$ diameter, $h$ highway dimension

## Discrete Fréchet Distance - Idea



Three possible legal steps:

## Discrete Fréchet Distance - Idea



Three possible legal steps: 1) one frog jumps

## Discrete Fréchet Distance - Idea



Three possible legal steps: 2) the other frog jumps

## Discrete Fréchet Distance - Idea



Three possible legal steps: 3) both frogs jump

## Discrete Fréchet Distance

Setting: metric graph $G$, distances w.r.t. shortest-path metric.

## Definition (Discrete Fréchet Distance)

The discrete Fréchet distance of two walks $P=\left\langle p_{1}, p_{2}, \ldots, p_{n}\right\rangle$ and $Q=\left\langle q_{1}, q_{2}, \ldots, q_{m}\right\rangle$ in $G$ is the minimum over the maximum pairwise distance of any legal traversal $\mathcal{T} \in P \times Q$ :

$$
D_{\mathcal{F}}(P, Q):=\min _{\mathcal{T}} \max _{\left(p_{i}, p_{j}\right) \in \mathcal{T}} \operatorname{dist}_{G}\left(p_{i}, q_{i}\right) .
$$



## Discrete Fréchet Distance

Setting: metric graph $G$, distances w.r.t. shortest-path metric.

## Definition (Discrete Fréchet Distance)

The discrete Fréchet distance of two walks $P=\left\langle p_{1}, p_{2}, \ldots, p_{n}\right\rangle$ and $Q=\left\langle q_{1}, q_{2}, \ldots, q_{m}\right\rangle$ in $G$ is the minimum over the maximum pairwise distance of any legal traversal $\mathcal{T} \in P \times Q$ :

$$
D_{\mathcal{F}}(P, Q):=\min _{\mathcal{T}} \max _{\left(p_{i}, p_{j}\right) \in \mathcal{T}} \operatorname{dist}_{G}\left(p_{i}, q_{i}\right) .
$$



## Discrete Fréchet Distance

Setting: metric graph $G$, distances w.r.t. shortest-path metric.

## Definition (Discrete Fréchet Distance)

The discrete Fréchet distance of two walks $P=\left\langle p_{1}, p_{2}, \ldots, p_{n}\right\rangle$ and $Q=\left\langle q_{1}, q_{2}, \ldots, q_{m}\right\rangle$ in $G$ is the minimum over the maximum pairwise distance of any legal traversal $\mathcal{T} \in P \times Q$ :

$$
D_{\mathcal{F}}(P, Q):=\min _{\mathcal{T}} \max _{\left(p_{i}, p_{j}\right) \in \mathcal{T}} \operatorname{dist}_{G}\left(p_{i}, q_{i}\right) .
$$



## Discrete Fréchet Distance

Setting: metric graph $G$, distances w.r.t. shortest-path metric.

## Definition (Discrete Fréchet Distance)

The discrete Fréchet distance of two walks $P=\left\langle p_{1}, p_{2}, \ldots, p_{n}\right\rangle$ and $Q=\left\langle q_{1}, q_{2}, \ldots, q_{m}\right\rangle$ in $G$ is the minimum over the maximum pairwise distance of any legal traversal $\mathcal{T} \in P \times Q$ :

$$
D_{\mathcal{F}}(P, Q):=\min _{\mathcal{T}} \max _{\left(p_{i}, p_{j}\right) \in \mathcal{T}} \operatorname{dist}_{G}\left(p_{i}, q_{i}\right) .
$$



## Free Space Matrix

## Definition (Free-Space Matrix)

Given two walks $P$ and $Q$ in $G, \delta>0$, the free-space matrix $M_{\delta} \in \mathbb{R}^{|P| \times|Q|}$ is defined by

$$
M_{\delta}[i, j]= \begin{cases}1 & \operatorname{dist}_{G}\left(p_{i}, q_{j}\right) \leq \delta \\ 0 & \text { else }\end{cases}
$$

G :


## Free Space Matrix

## Definition (Free-Space Matrix)

Given two walks $P$ and $Q$ in $G, \delta>0$, the free-space matrix $M_{\delta} \in \mathbb{R}^{|P| \times|Q|}$ is defined by

$$
M_{\delta}[i, j]= \begin{cases}1 & \operatorname{dist}_{G}\left(p_{i}, q_{j}\right) \leq \delta \\ 0 & \text { else }\end{cases}
$$



| $M_{2}:$ | 0 | 0 | 0 | 1 | 1 |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | 0 | 0 | 1 | 0 | 0 |
|  | 1 | 0 | 1 | 0 | 0 |
| $q_{1}$ | 1 | 1 | 0 | 0 | 0 |
|  | $p_{1}$ |  |  |  |  |

## Free Space Matrix

Definition (Free-Space Matrix)
Given two walks $P$ and $Q$ in $G, \delta>0$, the free-space matrix $M_{\delta} \in \mathbb{R}^{|P| \times|Q|}$ is defined by

$$
M_{\delta}[i, j]= \begin{cases}1 & \operatorname{dist}_{G}\left(p_{i}, q_{j}\right) \leq \delta \\ 0 & \text { else }\end{cases}
$$

Observation:

$$
\begin{aligned}
& D_{\mathcal{F}}(P, Q) \leq \delta \\
& \Leftrightarrow \quad \exists \text { legal traversal } \mathcal{T} \text { through } P \times Q \text { s.t. } M_{\delta}[i, j]=1 \\
& \quad \forall\left(p_{i}, q_{j}\right) \in \mathcal{T} .
\end{aligned}
$$

| $M_{2}:$ | 0 | 0 | 0 | 1 | 1 |
| ---: | :--- | :--- | :--- | :--- | :--- |
|  | 0 | 0 | 1 | 0 | 0 |
|  | 1 | 0 | 1 | 0 | 0 |
| $q_{1}$ | 1 | 1 | 0 | 0 | 0 |

## Free Space Matrix

Definition (Free-Space Matrix)
Given two walks $P$ and $Q$ in $G, \delta>0$, the free-space matrix $M_{\delta} \in \mathbb{R}^{|P| \times|Q|}$ is defined by

$$
M_{\delta}[i, j]= \begin{cases}1 & \operatorname{dist}_{G}\left(p_{i}, q_{j}\right) \leq \delta \\ 0 & \text { else }\end{cases}
$$

Observation:

$$
\begin{aligned}
& D_{\mathcal{F}}(P, Q) \leq \delta \\
& \Leftrightarrow \quad \exists \text { legal traversal } \mathcal{T} \text { through } P \times Q \text { s.t. } M_{\delta}[i, j]=1 \\
& \quad \forall\left(p_{i}, q_{j}\right) \in \mathcal{T} .
\end{aligned}
$$



## Sparse Shortest Path Hitting Sets

Definition (Sparse Shortest Path Hitting Set (SPHS))
For $r>0$ an $(h, r)$-SPHS is a set $C \subseteq V(G)$ s.t.

- $\left|B_{2 r}(v) \cap C\right| \leq h$ for all $v \in V(G)$,
- $V(P) \cap C \neq \emptyset$ for all "long (w.r.t. $r$ )" shortest paths $P$.



## $r$-significant paths

Definition ( $r$-significant path)
A shortest path $P^{\prime}$ is an $r$-witness for $P$ if $\ell\left(P^{\prime}\right)>r$ and $P=P^{\prime}$ or $P$ arises from $P^{\prime}$ by deleting one or both end vertices. $P$ is $r$-significant if it has an $r$-witness.


## Sparse Shortest Path Hitting Sets

Definition (Sparse Shortest Path Hitting Set (SPHS))
For $r>0$ an $(h, r)$-SPHS is a set $C \subseteq V(G)$ s.t.

- $\left|B_{2 r}(v) \cap C\right| \leq h$ for all $v \in V(G)$,
- $V(P) \cap C \neq \emptyset$ for all $r$-significant shortest paths $P$.


## Sparse Shortest Path Hitting Sets

Definition (Sparse Shortest Path Hitting Set (SPHS))
For $r>0$ an $(h, r)$-SPHS is a set $C \subseteq V(G)$ s.t.

- $\left|B_{2 r}(v) \cap C\right| \leq h$ for all $v \in V(G)$,
- $V(P) \cap C \neq \emptyset$ for all $r$-significant shortest paths $P$.

Idea: Highway dimension $\approx$ smallest $h$ s.t. ( $h, r$ )-SPHS exists for all $r>0$.

## Sparse Shortest Path Hitting Sets

Definition (Sparse Shortest Path Hitting Set (SPHS))
For $r>0$ an $(h, r)$-SPHS is a set $C \subseteq V(G)$ s.t.

- $\left|B_{2 r}(v) \cap C\right| \leq h$ for all $v \in V(G)$,
- $V(P) \cap C \neq \emptyset$ for all $r$-significant shortest paths $P$.

Idea: Highway dimension $\approx$ smallest $h$ s.t. ( $h, r$ )-SPHS exists for all $r>0$.
Theorem (Abraham, Delling, Fiat, Goldberg, Werneck)
In a graph with highway dimension $h$, we can compute a $(\mathcal{O}(h \log h), r)$-SPHS in polynomial runtime.

## The Algorithm

Given: shortest path $P$, arbitrary walk $Q$, value $\delta>0$
Goal: Decide whether $D_{\mathcal{F}}(P, Q) \leq \delta$ or $D_{\mathcal{F}}(P, Q)>\delta$.

## The Algorithm

Given: shortest path $P$, arbitrary walk $Q$, value $\delta>0$
Goal: Decide whether $D_{\mathcal{F}}(P, Q) \leq \frac{5}{2} \delta$ or $D_{\mathcal{F}}(P, Q)>\frac{3}{2} \delta$.

## The Algorithm

Given: shortest path $P$, arbitrary walk $Q$, value $\delta>0$
Goal: Decide whether $D_{\mathcal{F}}(P, Q) \leq \frac{5}{2} \delta$ or $D_{\mathcal{F}}(P, Q)>\frac{3}{2} \delta$.
1 compute $\left(h^{\prime}, \delta\right)$-SPHS $\rightarrow C$.

## The Algorithm

Given: shortest path $P$, arbitrary walk $Q$, value $\delta>0$
Goal: Decide whether $D_{\mathcal{F}}(P, Q) \leq \frac{5}{2} \delta$ or $D_{\mathcal{F}}(P, Q)>\frac{3}{2} \delta$.
1 compute $\left(h^{\prime}, \delta\right)$-SPHS $\rightarrow C$.
$\boxed{2}$ compute simplification of $P \rightarrow P^{\delta}$ :


## The Algorithm

Given: shortest path $P$, arbitrary walk $Q$, value $\delta>0$
Goal: Decide whether $D_{\mathcal{F}}(P, Q) \leq \frac{5}{2} \delta$ or $D_{\mathcal{F}}(P, Q)>\frac{3}{2} \delta$.
1 compute $\left(h^{\prime}, \delta\right)$-SPHS $\rightarrow C$.
$\boxed{2}$ compute simplification of $P \rightarrow P^{\delta}$ : visits endpoints of $P$ and $V(P) \cap C$.

$$
P^{\delta}, P:
$$



## The Algorithm

Given: shortest path $P$, arbitrary walk $Q$, value $\delta>0$
Goal: Decide whether $D_{\mathcal{F}}(P, Q) \leq \frac{5}{2} \delta$ or $D_{\mathcal{F}}(P, Q)>\frac{3}{2} \delta$.
1 compute $\left(h^{\prime}, \delta\right)$-SPHS $\rightarrow C$.
2 compute simplification of $P \rightarrow P^{\delta}$ : visits endpoints of $P$ and $V(P) \cap C$.
3 BFS through $M_{2 \delta}$ of $P^{\delta}$ and $Q \rightarrow D_{\mathcal{F}}\left(P^{\delta}, Q\right) \leq 2 \delta$ ?


## The Algorithm

Given: shortest path $P$, arbitrary walk $Q$, value $\delta>0$
Goal: Decide whether $D_{\mathcal{F}}(P, Q) \leq \frac{5}{2} \delta$ or $D_{\mathcal{F}}(P, Q)>\frac{3}{2} \delta$.
1 compute $\left(h^{\prime}, \delta\right)$-SPHS $\rightarrow C$.
2 compute simplification of $P \rightarrow P^{\delta}$ : visits endpoints of $P$ and $V(P) \cap C . \Rightarrow D_{\mathcal{F}}\left(P^{\delta}, P\right) \leq \frac{\delta}{2}$
3 BFS through $M_{2 \delta}$ of $P^{\delta}$ and $Q \rightarrow D_{\mathcal{F}}\left(P^{\delta}, Q\right) \leq 2 \delta$ ?


## The Algorithm

Given: shortest path $P$, arbitrary walk $Q$, value $\delta>0$
Goal: Decide whether $D_{\mathcal{F}}(P, Q) \leq \frac{5}{2} \delta$ or $D_{\mathcal{F}}(P, Q)>\frac{3}{2} \delta$.
1 compute $\left(h^{\prime}, \delta\right)$-SPHS $\rightarrow C$.
$\boxed{2}$ compute simplification of $P \rightarrow P^{\delta}$ : visits endpoints of $P$ and $V(P) \cap C . \Rightarrow D_{\mathcal{F}}\left(P^{\delta}, P\right) \leq \frac{\delta}{2}$
3 BFS through $M_{2 \delta}$ of $P^{\delta}$ and $Q \rightarrow D_{\mathcal{F}}\left(P^{\delta}, Q\right) \leq 2 \delta$ ? $\Delta$-inequality: $\Rightarrow D_{\mathcal{F}}(P, Q) \leq \frac{5}{2} \delta$ or $D_{\mathcal{F}}(P, Q)>\frac{3}{2} \delta$


## The Algorithm

Given: shortest path $P$, arbitrary walk $Q$, value $\delta>0$
Goal: Decide whether $D_{\mathcal{F}}(P, Q) \leq \frac{5}{2} \delta$ or $D_{\mathcal{F}}(P, Q)>\frac{3}{2} \delta$.
1 compute $\left(h^{\prime}, \delta\right)$-SPHS $\rightarrow C$. $\rightarrow$ polynomial
2 compute simplification of $P \rightarrow P^{\delta}$ : visits endpoints of $P$ and $V(P) \cap C . \Rightarrow D_{\mathcal{F}}\left(P^{\delta}, P\right) \leq \frac{\delta}{2}$
3 BFS through $M_{2 \delta}$ of $P^{\delta}$ and $Q \rightarrow D_{\mathcal{F}}\left(P^{\delta}, Q\right) \leq 2 \delta$ ? $\Delta$-inequality: $\Rightarrow D_{\mathcal{F}}(P, Q) \leq \frac{5}{2} \delta$ or $D_{\mathcal{F}}(P, Q)>\frac{3}{2} \delta$


## The Algorithm

Given: shortest path $P$, arbitrary walk $Q$, value $\delta>0$
Goal: Decide whether $D_{\mathcal{F}}(P, Q) \leq \frac{5}{2} \delta$ or $D_{\mathcal{F}}(P, Q)>\frac{3}{2} \delta$.
1 compute $\left(h^{\prime}, \delta\right)$-SPHS $\rightarrow C . \quad \rightarrow$ polynomial
$\boxed{2}$ compute simplification of $P \rightarrow P^{\delta}: \quad \rightarrow \mathcal{O}(|P|)$ visits endpoints of $P$ and $V(P) \cap C . \Rightarrow D_{\mathcal{F}}\left(P^{\delta}, P\right) \leq \frac{\delta}{2}$
3 BFS through $M_{2 \delta}$ of $P^{\delta}$ and $Q \rightarrow D_{\mathcal{F}}\left(P^{\delta}, Q\right) \leq 2 \delta$ ? $\Delta$-inequality: $\Rightarrow D_{\mathcal{F}}(P, Q) \leq \frac{5}{2} \delta$ or $D_{\mathcal{F}}(P, Q)>\frac{3}{2} \delta$


## The Algorithm

Given: shortest path $P$, arbitrary walk $Q$, value $\delta>0$
Goal: Decide whether $D_{\mathcal{F}}(P, Q) \leq \frac{5}{2} \delta$ or $D_{\mathcal{F}}(P, Q)>\frac{3}{2} \delta$.
1 compute $\left(h^{\prime}, \delta\right)$-SPHS $\rightarrow C . \quad \rightarrow$ polynomial
2 compute simplification of $P \rightarrow P^{\delta}: \quad \rightarrow \mathcal{O}(|P|)$ visits endpoints of $P$ and $V(P) \cap C . \Rightarrow D_{\mathcal{F}}\left(P^{\delta}, P\right) \leq \frac{\delta}{2}$
3 BFS through $M_{2 \delta}$ of $P^{\delta}$ and $Q \rightarrow D_{\mathcal{F}}\left(P^{\delta}, Q\right) \leq 2 \delta$ ?
$\Delta$-inequality: $\Rightarrow D_{\mathcal{F}}(P, Q) \leq \frac{5}{2} \delta$ or $D_{\mathcal{F}}(P, Q)>\frac{3}{2} \delta$ $\#($ non-zero entries in each row $) \leq h^{\prime}+2$


## The Algorithm

Given: shortest path $P$, arbitrary walk $Q$, value $\delta>0$
Goal: Decide whether $D_{\mathcal{F}}(P, Q) \leq \frac{5}{2} \delta$ or $D_{\mathcal{F}}(P, Q)>\frac{3}{2} \delta$.
1 compute $\left(h^{\prime}, \delta\right)$-SPHS $\rightarrow C . \quad \rightarrow$ polynomial
2 compute simplification of $P \rightarrow P^{\delta}: \quad \rightarrow \mathcal{O}(|P|)$ visits endpoints of $P$ and $V(P) \cap C . \Rightarrow D_{\mathcal{F}}\left(P^{\delta}, P\right) \leq \frac{\delta}{2}$
3 BFS through $M_{2 \delta}$ of $P^{\delta}$ and $Q \rightarrow D_{\mathcal{F}}\left(P^{\delta}, Q\right) \leq 2 \delta$ ?
$\Delta$-inequality: $\Rightarrow D_{\mathcal{F}}(P, Q) \leq \frac{5}{2} \delta$ or $D_{\mathcal{F}}(P, Q)>\frac{3}{2} \delta$ $\#($ non-zero entries in each row $) \leq h^{\prime}+2$
$\Rightarrow \mathcal{O}\left(|Q| h^{\prime}\right)$ steps


## The Algorithm

## Problems:

1 Computing $C$ can take long.

## The Algorithm

## Problems:

1 Computing $C$ can take long.

- Need to compute distances in $G$ during the BFS.


## The Algorithm

## Problems:

1 Computing $C$ can take long.
■ Need to compute distances in $G$ during the BFS.
Solutions:

## The Algorithm

## Problems:

1. Computing $C$ can take long.

- Need to compute distances in $G$ during the BFS.


## Solutions:

1 pre-compute $\varepsilon$-multiscale SPHS for $\varepsilon>1$ : $\left(h^{\prime}, \varepsilon^{i-1}\right)$-SPHS $C_{i}$ for $0 \leq i \leq\lceil\log D / \log \varepsilon\rceil$.
$D:=$ diameter of $G$.

## The Algorithm

## Problems:

1. Computing $C$ can take long.

- Need to compute distances in $G$ during the BFS.


## Solutions:

1 pre-compute $\varepsilon$-multiscale SPHS for $\varepsilon>1$ : $\left(h^{\prime}, \varepsilon^{i-1}\right)$-SPHS $C_{i}$ for $0 \leq i \leq\lceil\log D / \log \varepsilon\rceil$. In the algorithm: Choose $C_{i}$ such that $\varepsilon^{i-1} \approx \delta$.
$D:=$ diameter of $G$.

## The Algorithm

## Problems:

1. Computing $C$ can take long.

- Need to compute distances in $G$ during the BFS.


## Solutions:

1 pre-compute $\varepsilon$-multiscale SPHS for $\varepsilon>1$ : $\left(h^{\prime}, \varepsilon^{i-1}\right)$-SPHS $C_{i}$ for $0 \leq i \leq\lceil\log D / \log \varepsilon\rceil$.
In the algorithm: Choose $C_{i}$ such that $\varepsilon^{i-1} \approx \delta$.
■ Use oracle with $\mathcal{O}\left(h^{\prime} \log D\right)$ query time using a 2 -multiscale SPHS.
$D:=$ diameter of $G$.

## Final Result

## Theorem

$G$ metric graph with highway dimension $h, \varepsilon>0$.
Preprocessing $G$ in time polynomial in $|V(G)|$ and $1 / \log (1+\varepsilon)$ using $\mathcal{O}(|V(G)| \log D(1 / \log (1+\varepsilon)+h \log h))$ space.
$\Rightarrow$ decide for any shortest path $P$, walk $Q, \delta>0$, if $D_{\mathcal{F}}(P, Q)>\delta$ or $D_{\mathcal{F}}(P, Q) \leq\left(\frac{5}{3}+\varepsilon\right) \delta$ in $\mathcal{O}\left(|P|+|Q|(h \log h)^{2} \log D\right)$ time

## Final Result

## Theorem

$G$ metric graph with highway dimension $h, \varepsilon>0$.
Preprocessing $G$ in time polynomial in $|V(G)|$ and $1 / \log (1+\varepsilon)$ using
$\mathcal{O}(|V(G)| \log D(1 / \log (1+\varepsilon)+h \log h))$ space.
$\Rightarrow$ decide for any shortest path $P$, walk $Q, \delta>0$, if $D_{\mathcal{F}}(P, Q)>\delta$ or $D_{\mathcal{F}}(P, Q) \leq\left(\frac{5}{3}+\varepsilon\right) \delta$ in $\mathcal{O}\left(|P|+|Q|(h \log h)^{2} \log D\right)$ time

## Remark

Binary search $\Rightarrow\left(\frac{5}{3}+\varepsilon\right)$-approximation of $D_{\mathcal{F}}(P, Q)$.

## Final Result

|  | apx-factor | time |
| :---: | :---: | :---: |
| Driemel, van der Hoog, Rotenberg [2022] | $1+\varepsilon$ | $\mathcal{O}\left(\|G\| \log \|G\| / \sqrt{\varepsilon}+\|P\|+\frac{1}{\varepsilon}\|Q\|\right)$ |
| van der Hoog, Rotenberg, Wong [2023] | $1+\varepsilon$ | $\mathcal{O}\left(\frac{1}{\varepsilon}\|Q\|\left(T_{\text {dist }}+\log \|P\|\right)\right)$ |
| Driemel, Richter [2024] | $\frac{5}{3}+\varepsilon$ | $\mathcal{O}\left(\|P\|+\|Q\|(h \log h)^{2} \log D\right)$ |

Thank you for your attention!


Questions?

