# Approximating the Fréchet Distance for Low Highway Dimension Graphs

### Anne Driemel and Marena Richter

University of Bonn

EuroCG '24, March 2024

Problem Introduction	Fréchet Distance	Highway Dimension	The Algorithm
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### Overall problem

**Given:** Graph *G*, shortest path *P*, walk *Q*. **Goal:** Compute discrete Fréchet distance of *P* and *Q*.

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### Decision problem

**Given:** Graph *G*, shortest path *P*, walk *Q*,  $\delta > 0$ . **Goal:** Decide if  $D_{\mathcal{F}}(P, Q) \leq \delta$  or  $D_{\mathcal{F}}(P, Q) > \delta$ .

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**Given:** Graph *G*, shortest path *P*, walk *Q*,  $\delta > 0$ . **Goal:** Decide if  $D_{\mathcal{F}}(P, Q) \leq \alpha \cdot \delta$  or  $D_{\mathcal{F}}(P, Q) > \delta$  for some  $\alpha > 1$ .

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Related work for decision problem:

·	apx-factor	time
Driemel, van der Hoog, Rotenberg [2022]	1+arepsilon	$\mathcal{O}\left( \left  { \left  { \left  { \left  { \log \left  { \left  { \left  { \left $
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D diameter, h highway dimension

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## Discrete Fréchet Distance – Idea



Three possible legal steps:

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## Discrete Fréchet Distance - Idea



Three possible legal steps: 1) one frog jumps

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## Discrete Fréchet Distance - Idea



Three possible legal steps: 2) the other frog jumps

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## Discrete Fréchet Distance - Idea



### Three possible legal steps: 3) both frogs jump

## Discrete Fréchet Distance

Setting: metric graph G, distances w.r.t. shortest-path metric.

### Definition (Discrete Fréchet Distance)

$$D_{\mathcal{F}}(P,Q) \coloneqq \min_{\mathcal{T}} \max_{(p_i,p_j)\in\mathcal{T}} \operatorname{dist}_G(p_i,q_i).$$



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### Definition (Free-Space Matrix)

Given two walks P and Q in G,  $\delta > 0$ , the **free-space matrix**  $M_{\delta} \in \mathbb{R}^{|P| \times |Q|}$  is defined by

$$\mathcal{M}_{\delta}[i,j] = egin{cases} 1 & ext{dist}_{G}(p_{i},q_{j}) \leq \delta \ 0 & ext{else} \end{cases}$$



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Observation:	$M_2$ :	0	0	0	1	1
$D_{\mathcal{F}}\left(\mathcal{P},\mathcal{Q} ight)\leq\delta$		0	0	1	0	0
$\Leftrightarrow \exists \text{ legal traversal } \mathcal{T} \text{ through } P \times Q \text{ s.t. } M_{\delta}[i,j] = 1$		1	0	1	0	0
$\forall (\pmb{p}_i, \pmb{q}_j) \in \mathcal{T}.$	$q_1$	1	1	0	0	0

 $p_1$ 

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### **Observation:**

 $D_{\mathcal{F}}(P,Q) \leq \delta$ 

$$\Leftrightarrow \exists \text{ legal traversal } \mathcal{T} \text{ through } P \times Q \text{ s.t. } M_{\delta}[i,j] = 1$$
$$\forall (p_i, q_i) \in \mathcal{T}.$$

$$M_2: \begin{array}{ccccccc} 0 & 0 & 0 & 1 & + 1 \\ 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 \\ q_1 & 1 & + 1 & 0 & 0 & 0 \end{array}$$

 $p_1$ 

Highway Dimension ●00

# Sparse Shortest Path Hitting Sets

#### Definition (Sparse Shortest Path Hitting Set (SPHS))

For r > 0 an (h, r)-**SPHS** is a set  $C \subseteq V(G)$  s.t.

- $|B_{2r}(v) \cap C| \le h \text{ for all } v \in V(G),$
- $V(P) \cap C \neq \emptyset$  for all "long (w.r.t. r)" shortest paths P.



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## r-significant paths

### Definition (*r*-significant path)

A shortest path P' is an *r*-witness for P if  $\ell(P') > r$  and P = P' or P arises from P' by deleting one or both end vertices. P is *r*-significant if it has an *r*-witness.



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Idea: Highway dimension  $\approx$  smallest *h* s.t. (*h*, *r*)-SPHS exists for all *r* > 0.

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**Idea:** Highway dimension  $\approx$  smallest *h* s.t. (*h*, *r*)-SPHS exists for all *r* > 0.

### Theorem (Abraham, Delling, Fiat, Goldberg, Werneck)

In a graph with highway dimension h, we can compute a  $(\mathcal{O}(h \log h), r)$ -SPHS in polynomial runtime.

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**Given:** shortest path *P*, arbitrary walk *Q*, value  $\delta > 0$ **Goal:** Decide whether  $D_{\mathcal{F}}(P,Q) \leq \frac{5}{2}\delta$  or  $D_{\mathcal{F}}(P,Q) > \frac{3}{2}\delta$ .

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**2** compute simplification of  $P \rightarrow P^{\delta}$ :



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Given: shortest path P, arbitrary walk Q, value δ > 0
Goal: Decide whether D<sub>F</sub> (P, Q) ≤ <sup>5</sup>/<sub>2</sub>δ or D<sub>F</sub> (P, Q) > <sup>3</sup>/<sub>2</sub>δ.
I compute (h', δ)-SPHS → C.
2 compute simplification of P → P<sup>δ</sup>: visits endpoints of P and V(P) ∩ C.



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**3** BFS through  $M_{2\delta}$  of  $P^{\delta}$  and  $Q \rightarrow D_{\mathcal{F}}\left(P^{\delta}, Q\right) \leq 2\delta$  ?



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 $P^{\delta}$   $P^{+}$ 

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### **Problems:**

**1** Computing C can take long.

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### Solutions:

I pre-compute  $\varepsilon$ -multiscale SPHS for  $\varepsilon > 1$ :  $(h', \varepsilon^{i-1})$ -SPHS  $C_i$  for  $0 \le i \le \lceil \log D / \log \varepsilon \rceil$ .

 $D \coloneqq$  diameter of G.

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- **2** Use oracle with  $\mathcal{O}(h' \log D)$  query time using a 2-multiscale SPHS.

D := diameter of G.

# Final Result

#### Theorem

*G* metric graph with highway dimension h,  $\varepsilon > 0$ .

Preprocessing G in time polynomial in |V(G)| and  $1/\log(1+\varepsilon)$  using  $\mathcal{O}(|V(G)|\log D(1/\log(1+\varepsilon) + h \log h))$  space.

⇒ decide for any shortest path P, walk Q,  $\delta > 0$ , if  $D_{\mathcal{F}}(P, Q) > \delta$  or  $D_{\mathcal{F}}(P, Q) \le (\frac{5}{3} + \varepsilon)\delta$  in  $\mathcal{O}(|P| + |Q|(h \log h)^2 \log D)$  time.

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#### Remark

Binary search  $\Rightarrow (\frac{5}{3} + \varepsilon)$ -approximation of  $D_{\mathcal{F}}(P, Q)$ .

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# Final Result

	apx-factor	time
Driemel, van der Hoog, Rotenberg [2022]	1+arepsilon	$\mathcal{O}\left( \left  {\left. {G}  ight \log \left  {G}  ight /\sqrt arepsilon + \left  {P}  ight  + rac 1 arepsilon \left  {Q}  ight }  ight)$
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Thank you for your attention!



Questions?